# What is Linear Algebra?

- Wikipedia:
  - Linear algebra is the branch of mathematics concerning vector spaces, often finite or countably infinite dimensional, as well as linear mappings between such spaces. Such an investigation is initially motivated by a system of linear equations containing several unknowns. Such equations are naturally represented using the formalism of matrices and vectors.



### CHAPTER 7 VECTOR SPACES Section 7.1 Vector Spaces and Their Subspaces

#### **Definition. (Vector Space)**

A vector space V over a field  $\mathcal{F}$  with two operations **vector addition**"+" and **scalar multiplication**"·" defined so that

1. 
$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$
 for all  $\mathbf{u}, \mathbf{v} \in V$ .

2. 
$$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w}).$$

- 3. There is an element in V, denoted **0**, such that  $\mathbf{u} + \mathbf{0} = \mathbf{u}$  for any  $\mathbf{u} \in V$ .
- 4. For any  $\mathbf{u} \in V$ , there exists an element, denoted  $-\mathbf{u}$ , such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ .

5. 
$$1 \cdot \mathbf{u} = \mathbf{u}$$
 for all  $\mathbf{u} \in V$ .

6. 
$$(ab) \cdot \mathbf{u} = a \cdot (b\mathbf{u})$$
 for all  $a, b \in \mathcal{F}$  and  $\mathbf{u} \in V$ .

7. 
$$a \cdot (\mathbf{u} + \mathbf{v}) = a \cdot \mathbf{u} + a \cdot \mathbf{v}$$
 for all  $a \in \mathcal{F}$  and  $\mathbf{u}, \mathbf{v} \in V$ .

8. 
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Four essential components in the definition of vector spaces

- 1. The set of vectors: V.
- 2. The field:  $\mathcal{F}$ . (along with "+" and "." operations thereof)
- 3. Addition operator "+":  $V \times V \rightarrow V$
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**Proposition.** ( $\mathcal{R}^n$ ,  $\mathcal{R}$ , "+", ".") is a vector space where vector addition "+" and scalar multiplication "." were defined as in Chapter 1.

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**Question.** Are there other forms of vector spaces?

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#### **Theorem 1.1** (Properties of Matrix Addition and Scalar Multiplication)

Let A, B, and C be  $m \times n$  matrices, and let s and t be any scalars. Then

(a) 
$$A + B = B + A$$
. (commutative law of matrix addition)

(b) (A+B) + C = A + (B+C). (associative law of matrix addition)

$$(c)A + O = A.$$
  
(d)A + (-A) = O.

(e)(st)A = s(tA).

(f)s(A+B) = sA + sB.

(g)(s+t)A = sA + tA.

Consider the case where n = 1, Then *A*, *B*, *C* are all vectors in  $\mathcal{R}^m$ .

5

Properties:

- 1.  $\mathcal{R}^n$  is a vector space under the operations of sum and scalar multiplication defined in Chapter 1.
- 2.  $\mathcal{M}_{m \times n}$  is a vector space under the operations of matrix addition and multiplication of a matrix by a scalar.
- 3. Any subspace of  $\mathcal{R}^n$  is a vector space.

#### **Definition. (Function Space)**

Given a set S, let  $\mathcal{F}(S) = \{f(\cdot) | f(t) \in \mathcal{R}, \forall t \in S\}$ , and let there be two operations on  $\mathcal{F}(S)$ : 1.  $\forall f, g \in \mathcal{F}(S)$ , the sum f + g satisfies  $(f + g)(t) = f(t) + g(t), \forall t \in S$ 2.  $\forall f \in \mathcal{F}(S)$  and  $a \in \mathcal{R}$ , the scalar multiple of satisfies  $(af)(t) = a(f(t)), \forall t \in \mathcal{F}(S)$ S.

Then  $\mathcal{F}(S)$  is called a **function space**.

### Theorem 7.1

 $\mathcal{F}(S)$  is a vector space.

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Proof Clearly,  $f + g \in \mathcal{F}(S)$  and  $af \in \mathcal{F}(S)$ . The Axioms 1 and 3 are verified below. You verify others. Axiom 1:  $(f + g)(t) = f(t) + g(t) = g(t) + f(t) = (g + f)(t) \forall t \in S$   $\Rightarrow f + g = g + f \quad \forall f, g \in F(S)$ . Axiom 3: define  $\mathbf{0}(\cdot) \in \mathcal{F}(S)$  as  $\mathbf{0}(t) = 0 \forall t \in S$   $\Rightarrow (f + \mathbf{0})(t) = f(t) + \mathbf{0}(t) = f(t) + 0 = f(t)$  $\Rightarrow f + \mathbf{0} = f \quad \forall f \in \mathcal{F}(S)$ .

#### Example

For any given positive integers m and n, let  $\mathcal{M}_{m \times n}$  denote the set of all  $m \times n$  real matrices. Then  $(\mathcal{M}_{m \times n}, \mathcal{R}, +, \cdot)$  is a vector space.

# Definition

 $\mathcal{L}(\mathcal{R}^n, \mathcal{R}^m) = \{ \text{all linear transformations from } \mathcal{R}^n \text{ to } \mathcal{R}^m \}$ 

Property:  $\mathcal{L}(\mathcal{R}^n, \mathcal{R}^m)$  is a vector space under the operations of addition of linear transformations and the product of a linear transformation by a scalar.

**Proof** You show it, noting that the "zero vector" is  $T_0$ .

#### Definition

 $\mathcal{P} = \{ \text{all polynomials in the variable } x \}.$ 

Property: *I* is a vector space with the usual definitions of polynomial addition and the product of a polynomial by a scalar. *Proof* You show it, noting that the "zero vector" is p(x) = 0, the zero polynomial (whose degree is defined to be -∞).

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Question: Why isn't there an axiom like  $0 \cdot \mathbf{v} = \mathbf{0}$  or  $a \cdot \mathbf{0} = \mathbf{0}$ 

#### Theorem 7.2

Let V be a vector space. Then for any  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  in V, and any scalar  $a \in \mathcal{F}$ , the following are true.

(a) If  $\mathbf{u} + \mathbf{v} = \mathbf{w} + \mathbf{v}$ , then  $\mathbf{u} = \mathbf{w}$ . (right cancellation law)

(b) If  $\mathbf{u} + \mathbf{v} = \mathbf{u} + \mathbf{w}$ , then  $\mathbf{v} = \mathbf{w}$ . (left cancellation law)

(c) The zero vector  $\mathbf{0}$  is unique, that is, it is the only vector in V that satisfies axiom 3.

(d) Each vector in V has exactly one additive inverse.

(e) 
$$0 \cdot \mathbf{v} = \mathbf{0}$$
.  
(f)  $a \cdot \mathbf{0} = \mathbf{0}$ .  
(g)  $(-1) \cdot \mathbf{v} = -\mathbf{v}$ .  
(h)  $(-a) \cdot \mathbf{v} = a \cdot (-\mathbf{v}) = -(a \cdot \mathbf{v})$ .  

$$\int \mathbf{A} \mathbf{x}^{10m3} \int \mathbf{A}^{10m4} \int \mathbf{x}^{10m4} \mathbf{x}^{10m2} \mathbf{x}^{10m3} \mathbf{x}^{10m4} \mathbf{x}^{10m3} \mathbf$$

(by axiom 3)**Proof** (a) u = u + 0= u + (v + (-v)) (by axiom 4) = (**u** + **v**) + (-**v**)) (by axiom 2) = (**w** + **v**) + (-**v**)) = w + (v + (-v)) (by axiom 2)  $= \mathbf{w} + \mathbf{0}$  (by axiom 4) (by axiom 3)  $= \mathbf{w}$ . (b) Similar to (a). You show it. (c) Suppose 0' and 0 are such that  $\mathbf{u} + \mathbf{0'} = \mathbf{u} = \mathbf{u} + \mathbf{0} \forall \mathbf{u} \in V$ .  $\Rightarrow$  **0**' = **0** by (b). (d) Similar to (c). You show it. (e) 0v + 0v = (0+0)v (by axiom 8)  $= 0\mathbf{v}$  (property of 0) = 0 + 0v. (by axioms 3 and 1)  $\Rightarrow 0\mathbf{v} = \mathbf{0}$  by (a). (f)  $0 + a0 = a0 = a(0 + 0) = a0 + a0 \Rightarrow a0 = 0$  by (a). (g)  $\mathbf{v} + (-1)\mathbf{v} = (1)\mathbf{v} + (-1)\mathbf{v} = (1 + (-1))\mathbf{v} = 0\mathbf{v} = \mathbf{0}$  $\Rightarrow$  (-1)**v** = -**v** by (d). 13 (h) Similar to (g). You show it.

# **Definition.** (Subspace)

A subset W of a vector space V is called a **subspace** of V if W satisfies the following three properties.

W

\_0

- 1. The zero vector of V is in W.
- 2. For all  $\mathbf{u}, \mathbf{v}$  in  $W, \mathbf{u} + \mathbf{v}$  is in W.
- 3. For all **u** in W and any scalar  $c, c \cdot \mathbf{u}$  is in W.



- 1. A subspace is itself a vector space.
- 2. V is the largest subspace of a vector space V.
- 3. The zero subspace  $\{0\}$  is a subspace of any vector space V.

Example: Given  $S \neq \emptyset$  and  $s_0 \in S$ ,  $W = \{f(\cdot) \mid f(s_0) = 0\} \subseteq \mathcal{F}(S)$  is a subspace of  $\mathcal{F}(S)$  since for all  $f(\cdot), g(\cdot) \in W$  and  $a \in \mathcal{R}$ ,  $(f+g)(s_0) = f(s_0) + g(s_0) = 0 + 0 = 0$ , and  $(af)(s_0) = af(s_0) = a \cdot 0 = 0.$ 

Example: Define a trace of an  $n \ge n$  matrix A as trace  $A = a_{11} + a_{22} + \dots + a_{nn}$ . Then,  $W = \{A \mid \text{trace } A = 0\} \subseteq \mathbb{R}^{n \times n}$  is a subspace of  $\mathbb{R}^{n \times n}$  since for all  $A, B \in W$  and  $c \in \mathbb{R}$ , trace(A + B) = trace A + trace B = 0 + 0 = 0, and

trace 
$$(cA) = c \cdot \text{trace } A = c \cdot 0 = 0.$$

Example:  $C(\mathcal{R}) = \{ all continuous functions mapping from \mathcal{R} to \mathcal{R} \}$ is a subspace of  $\mathcal{F}(\mathcal{R})$ , since the sum of two continuous functions is a continuous function, and any scalar multiple of a continuous function is a continuous function.

 $\Rightarrow C(\mathcal{R})$  is a vector space.

Example:  $\mathcal{P}_n = \{ \text{all polynomials in the variable } x \text{ with degree } \le n \}$ is a subspace of  $\mathcal{P}$ .  $\Rightarrow \mathcal{P}_n \text{ is a vector space.}$ 

Example: Let  $\mathcal{P}_n = \{ \text{all polynomials in the variable } x \text{ with degree} = n \}$ Is  $\mathcal{P}_n$  a subspace of  $\mathcal{P}$ ? Is  $\mathcal{P}_n$  a vector space.

$$(x^2+1)+(-x^2+1)=2$$

17

#### **Definition. (Linear Combination)**

A vector **v** is a **linear combination** of the vectors of a (possibly **infinite**) subset S of a vector space V if there exist (**finite number of**) vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  in S and scalars  $c_1, c_2, \dots, c_n$  such that

 $\mathbf{v} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_n \mathbf{v}_n.$ 

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Example: A linear combination in the vector space  $\mathcal{R}^{2\times 2}$ 

$$\begin{bmatrix} -1 & 8\\ 2 & -2 \end{bmatrix} = 2 \begin{bmatrix} 1 & 3\\ 1 & -1 \end{bmatrix} + (-1) \begin{bmatrix} 4 & 0\\ 1 & 1 \end{bmatrix} + (1) \begin{bmatrix} 1 & 2\\ 1 & 1 \end{bmatrix}$$
$$S = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$
$$\subseteq \mathbb{R}^{2\times 2}$$

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Example: A linear combination in the vector space  $\boldsymbol{\mathcal{F}}$ 

$$f(x) = 2 + 3x - x^{2} = (2)1 + (3)x + (-1)x^{2} + (0)x^{3}$$

$$S_{3} = \{1, x, x^{2}, x^{3}\}$$

$$\Rightarrow \mathscr{P}_{3} = \text{the set of all linear combinations of the vectors in } S_{3}.$$

$$S = \{1, x, \underline{x^{2}}, \dots, x^{n}, \dots\}$$

$$\Rightarrow \text{ any polynomial is a linear combination of the vectors in } S.$$

$$u_{n} x' + u_{n} x'' + \dots + u_{1} x + u_{0} c p$$
  
+  $x + \frac{1}{2} x^{2} + \frac{1}{3!} x^{3} + \frac{1}{4!} x^{4} + \dots = e^{x} \& p$ 

# **Definition. (Span)**

The **span** of a nonempty subset S of a vector space V is the set of all linear combinations of vectors in S. This set is denoted Span S:

Example: Span 
$$\{1, x, x^2, x^3\} = \mathcal{P}_3$$
 Span  $\{1, x, x^2, \dots, x^n, \dots\} = \mathcal{P}_3$ 

Example: For all  $A \in \text{Span } S$ , with  $\Im = \{ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \in \mathbb{R}^{2\times 2}$ ,

$$A = a \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} a & b \\ c & -a \end{bmatrix}$$
$$\Rightarrow \text{Span } S = \{A \mid \text{trace } A = 0, A \in \mathcal{R}^{2 \times 2}\}, \text{ a subspace of } \mathcal{R}^{2 \times 2}.$$

Question:

Let *V* be a vector space and *W* be the span of a subset *S*. Is *W* a subspace of *V*?

21

#### Theorem 7.3

The span of a nonempty subset of a vector space V is a subspace of V.

*Proof* Extend the proof of Theorem 4.1 in Section 4.1.

(1) 
$$\underline{O} \in W$$
  
(2)  $\underline{V} + \underline{V} \in W$   
(3)  $\underline{C} - \underline{V} \in W$   
(4)  $\underline{V} = \underline{V} + \underline{V} \in W$   
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Example: the space of trigonometric polynomials

 $\mathcal{T}[0, 2\pi] = \text{Span } \{1, \cos t, \sin t, \cos 2t, \sin 2t, \cdots, \cos nt, \sin nt, \cdots \}$ is a subspace of  $\mathcal{F}([0, 2\pi])$ ,

#### **Homework Set for Section 7.1**

Section 7.1: Problems 28, 30, 32, 55-59, 79-82, 91, 92.